PPM (Pulse Position Modulation)

Young W. Lim

October 25, 2013

(ロ)、(型)、(E)、(E)、 E) の(()

Copyright (c) 2011-2013 Young W. Lim. Permission is granted to copy, distribute and/or modify this document under the terms of the GNU Free Documentation License, Version 1.2 or any later version published by the Free Software Foundation; with no Invariant Sections, no Front-Cover Texts, and no Back-Cover Texts. A copy of the license is included in the section entitled "GNU Free Documentation License".

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQ@

Generating the PDM Signal

- the message signal m(t)
- the PPM signal s(t)
- the standard pulse of interest g(t)

The Pulse Duration Modulation (PDM)

- use the samples of the message signal
- to vary the duration of the individual pulses g(t)
- the modulating signal m(t) may vary the time of occurrence of

◆□▶ ◆□▶ ◆□▶ ◆□▶ □ ○ ○ ○

- the leading edge
- the trailing edge
- both edges of the pulse g(t)

Generating the PPM Signal

- the message signal m(t)
- the PPM signal s(t)
- the standard pulse of interest g(t)

The Pulse Position Modulation (PPM)

- use the samples of the message signal
- to vary the position of the individual pulses g(t)
- relative to its unmodulated time of occurrence
- can reduce the power compared to PDM by subtracting the unused power

◆□▶ ◆□▶ ◆□▶ ◆□▶ □ ○ ○ ○

The Periodic Pulse Carrier

- the message signal m(t)
- the PPM signal s(t)
- the standard pulse of interest g(t)
- the periodic pulse carrier : $\sum_{n=-\infty}^{\infty} g([t-nT_s])$
- the sampled values at time nT_s : $m(nT_s)$
- the sensitivity factor : k_p
- the shifted pulse carrier : $s(t) = \sum_{n=-\infty}^{\infty} g([t nT_s] k_p m(nT_s))$

A D N A 目 N A E N A E N A B N A C N

Noverlapping Condition

• the shifted pulse carrier : $s(t) = \sum_{n=-\infty}^{\infty} g([t - nT_s] - k_p m(nT_s))$



▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

PPM Signal

- the message signal m(t)
- the PPM signal s(t)
- the standard pulse of interest g(t)

PPM Signal

$$s(t) = \sum_{n=-\infty}^{\infty} g\left(\left[t - nT_s \right] - k_p m(nT_s) \right)$$
$$g(t) = 0, \qquad |t| > \frac{T_s}{2} - k_p |m(t)|_{max}$$
$$k_p |m(t)|_{max} < \frac{T_s}{2}$$

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

Reference

[1] S. Haykin, M Moher, "Introduction to Analog and Digital Communications", 2ed