

Problem Representation

- Monkey and Banana

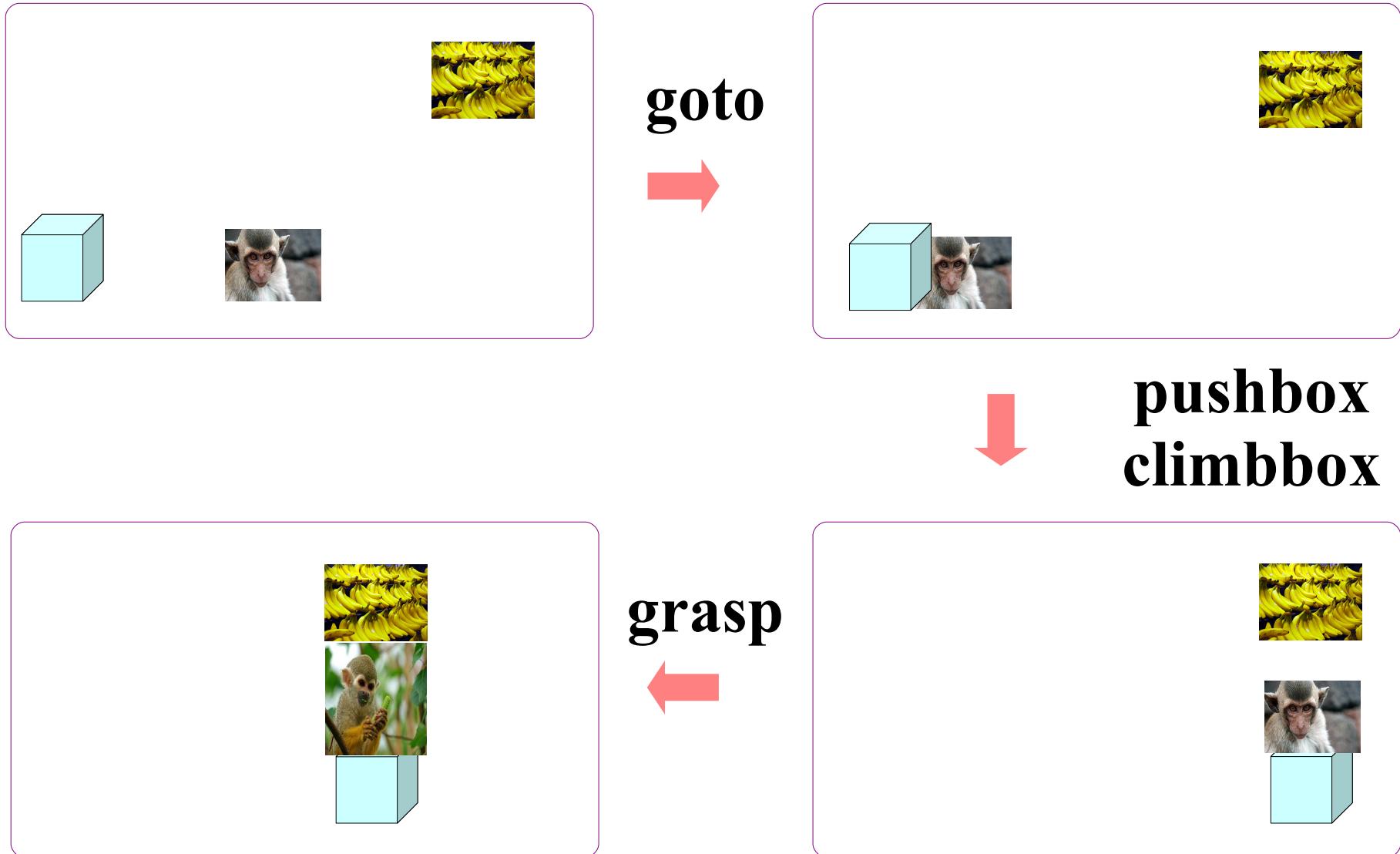
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Monkey and Banana



Monkey and Banana - State

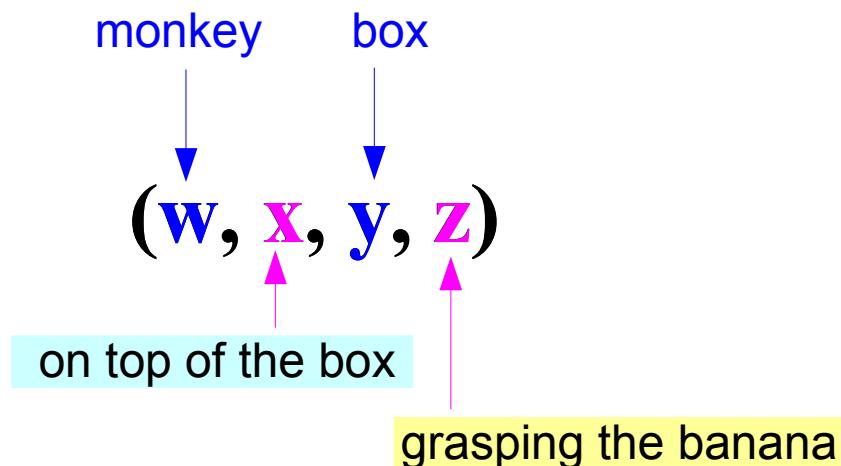
(w, x, y, z)

w: the position of the monkey (horizontal, vertical)

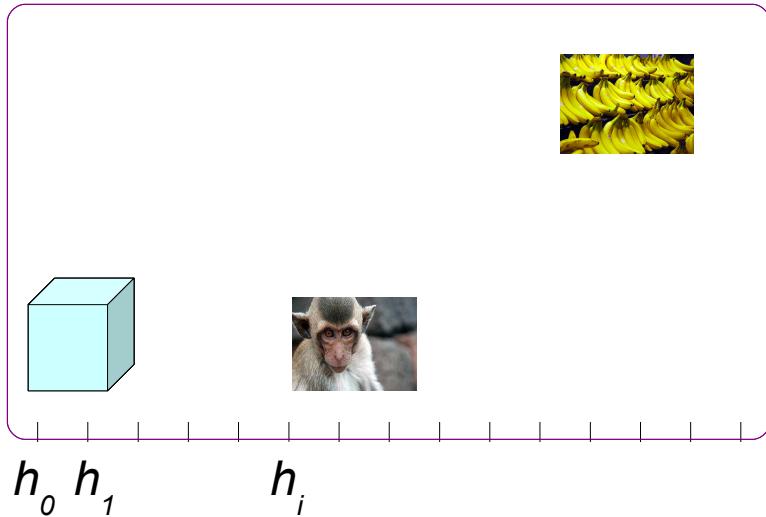
x: monkey on top of the box (1 or 0)

y: the position of the box (horizontal, vertical)

z: monkey grasping the banana (1 or 0)



Monkey and Banana – too many states



$(h_o, 0, h_o, 0)$

Too many states

$(h_1, 0, h_o, 0)$

$(h_2, 0, h_o, 0)$

$(h_3, 0, h_o, 0)$

$(h_i, 0, h_o, 0)$

$(h_3, 0, h_o, 0)$

$\xrightarrow{goto_h_3-h_2} (h_2, 0, h_o, 0)$

Too many operators

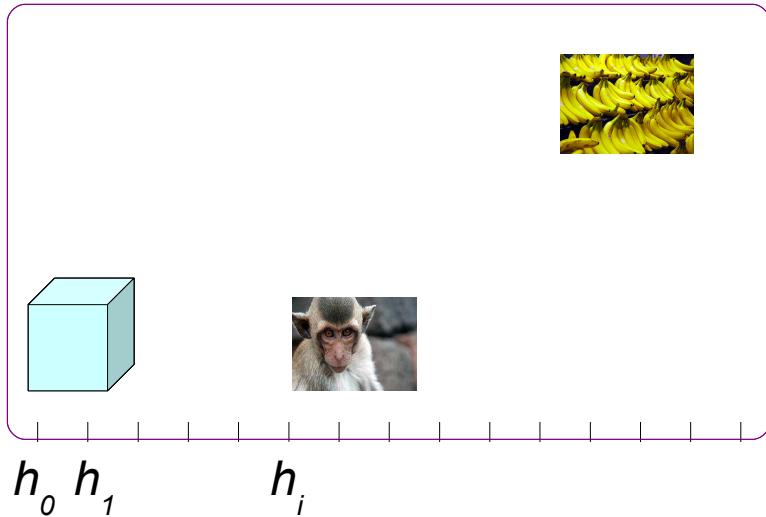
$(h_2, 0, h_o, 0)$

$\xrightarrow{goto_h_2-h_1} (h_1, 0, h_o, 0)$

$(h_1, 0, h_o, 0)$

$\xrightarrow{goto_h_1-h_0} (h_o, 0, h_o, 0)$

Monkey and Banana – Schema



Instances

- $(h_0, 0, h_o, 0)$
- $(h_1, 0, h_o, 0)$
- $(h_2, 0, h_o, 0)$
- $(h_3, 0, h_o, 0)$
- $(h_i, 0, h_o, 0)$

Schema

$(w, 0, y, 0)$



variables

- $(h_3, 0, h_o, 0)$
- $(h_2, 0, h_o, 0)$
- $(h_1, 0, h_o, 0)$

$goto(h_o)$

$goto(h_o)$

$goto(h_o)$

Instances

- $(h_0, 0, h_o, 0)$
- $(h_0, 0, h_o, 0)$
- $(h_0, 0, h_o, 0)$

Operator Schema

$goto(u)$



variables

Monkey and Banana – Operator Schema

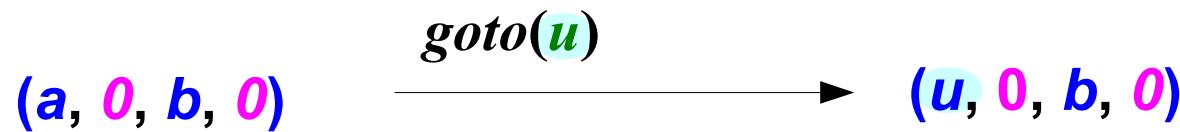
$(w, 0, y, z)$ $goto(u)$ \rightarrow $(u, 0, y, z)$

$(w, 0, w, z)$ $pushbox(v)$ \rightarrow $(v, 0, v, z)$

$(w, 0, w, z)$ $climbbox$ \rightarrow $(w, 1, w, z)$

$(c, 1, c, 0)$ $grasp$ \rightarrow $(c, 1, c, 1)$

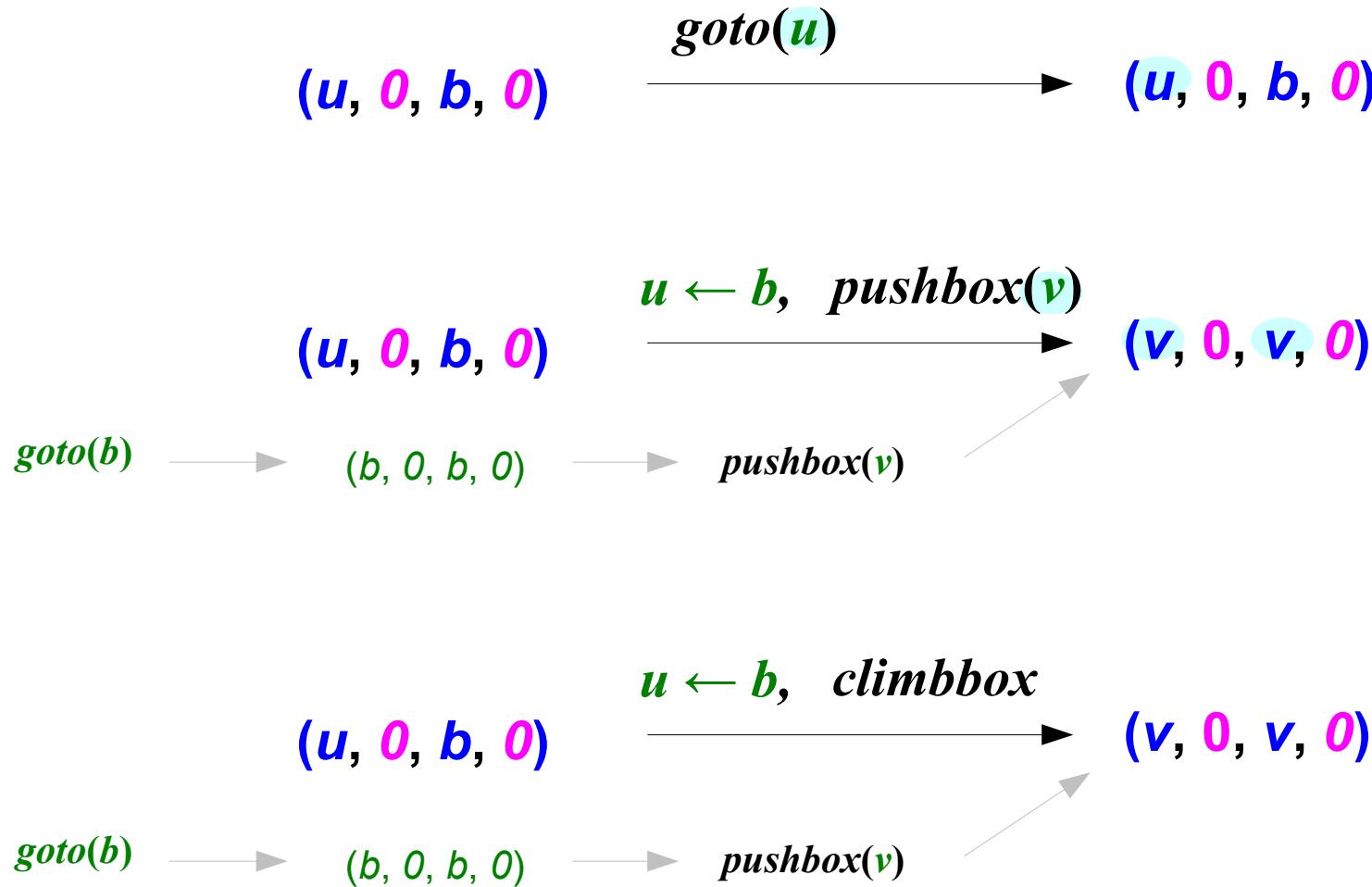
Monkey and Banana – (a, 0, b, 0)



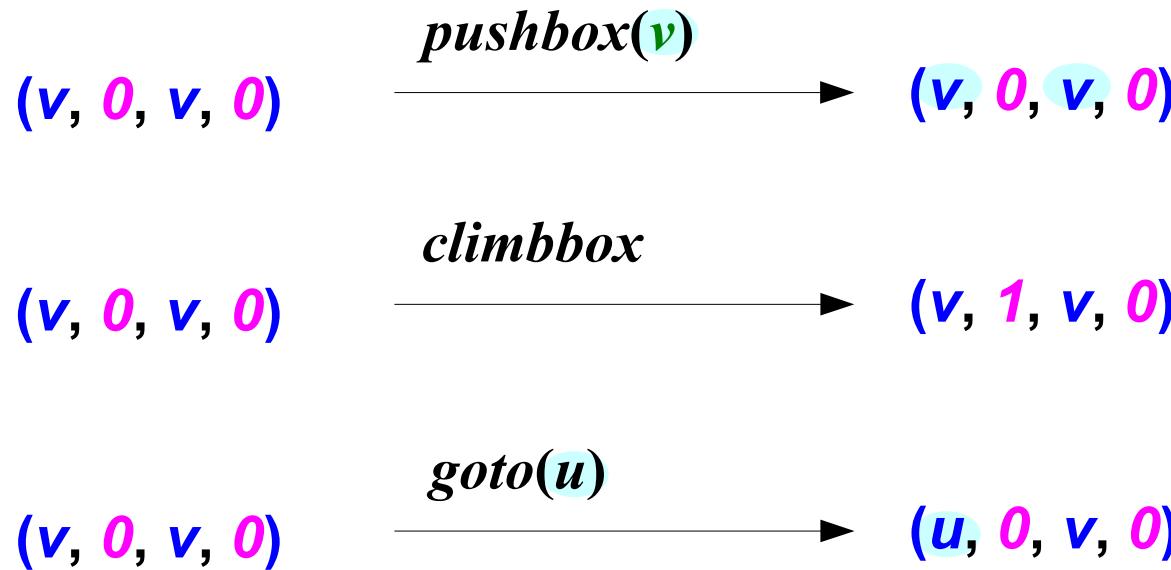
a, b, c : constants

u, v : variables

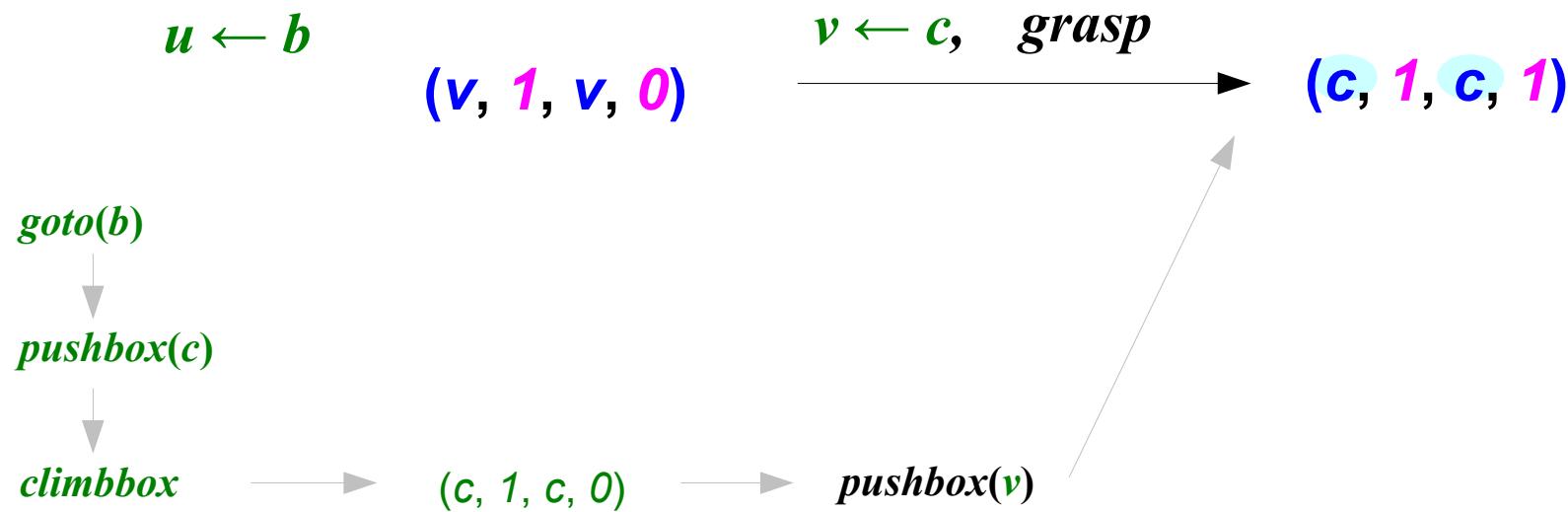
Monkey and Banana – (u, 0, b, 0)



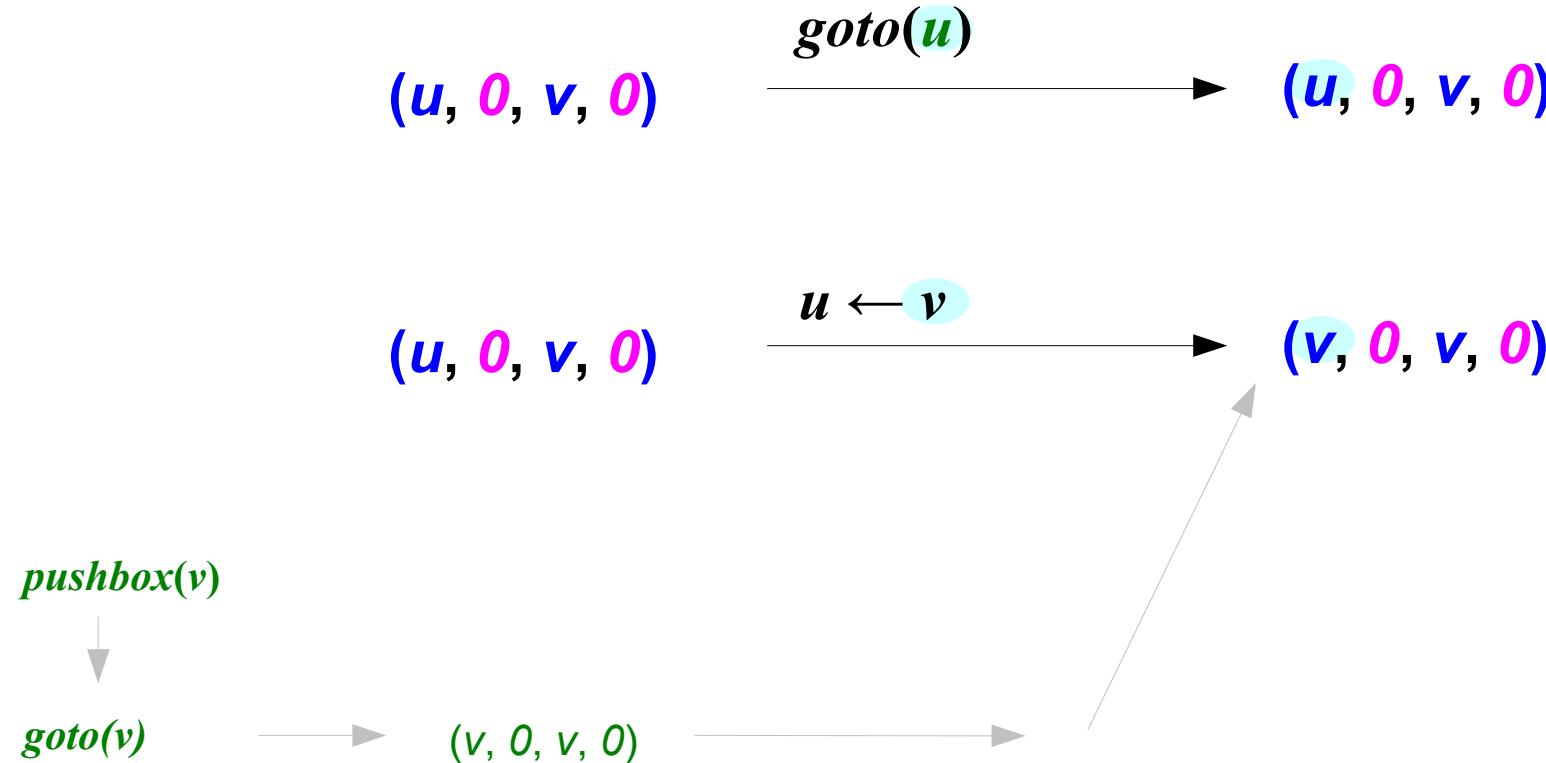
Monkey and Banana – (v, 0, v, 0)



Monkey and Banana – (v , 1, v , 0)



Monkey and Banana – (u, 0, v, 0)



References

- [1] <http://en.wikipedia.org/>
- [2] 인공지능개론, 이광형, 조충호, 흥릉과학출판사, 2000