

Ergodic Random Processes

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Based on
Probability, Random Variables and Random Signal Principles,
P.Z. Peebles,Jr. and B. Shi

Outline

- 1 Averages and Ergodicity
- 2 Mean Ergodic Processes
- 3 Correlation Ergodic Processes

Sample Average

N Gaussian random variables

Definition

The sample average

$$\overline{m}_X(t) = \frac{1}{N} \sum_{i=1}^N X_i(t)$$

N independent sample realizations of the process

$X_i(t)$ for $i = 1, \dots, N$

each realization is a time function

it is difficult to get many sample realizations

Time Average

N Gaussian random variables

Definition

The time average

$$A_T[\bullet] = \frac{1}{2T} \int_{-T}^T [\bullet] dt$$

average over time of a single realization

Time-Autocorrelation Function

N Gaussian random variables

Definition

The time average

$$\bar{x}_T = A_T[x(t)] = \frac{1}{2T} \int_{-T}^T x(t) dt$$

The time autocorrelation function

$$R_T(\tau) = A_T[x(t)x(t+\tau)] = \frac{1}{2T} \int_{-T}^T x(t)x(t+\tau) dt$$

Stationary Processes

N Gaussian random variables

Definition

first order stationary processes

$$m_X(t) = E[X(t)] = \bar{X} = \text{constant}$$

second order stationary processes

$$R_{XX}(t, t + \tau) = E[X(t)X(t + \tau)] = R_{XX}(\tau)$$

Stationary Processes Example

N Gaussian random variables

Definition

As an example of a stationary process for which any single realisation has an apparently noise-free structure, let Y have a uniform distribution on $(0, 2\pi]$ and define the time series $X(t)$ by

$$X(t) = \cos(t + Y)$$

Then $X(t)$ is strictly stationary.

Expectation of Time-Autocorrelation Function

N Gaussian random variables

Definition

assuming the expectation can be brought inside the integrals

$$E[\bar{x}_T] = A_T[E[x(t)]] = \bar{X}$$

$$E[R_T(\tau)] = A_T[E[x(t)x(t+\tau)]] = R_{XX}(\tau)$$

- \bar{x}_T : a unbiased estimate of \bar{X}
- \bar{X} - the process mean
- $R_T(\tau)$: a unbiased estimate of $R_{XX}(\tau)$
- $R_{XX}(\tau)$ - the autocorrelation of time lag τ

Convergence in square

N Gaussian random variables

Definition

the conditions under which random sequences of time average $A[\bullet]$ converge as $T \rightarrow \infty$

convergence in square

A **random sequence** X_n is said to **converge** to a **random variable** X in mean square if

$$\lim_{n \rightarrow \infty} E[(X_n - X)^2] = 0$$

$$A[\bullet] = \lim_{n \rightarrow \infty} A_T[\bullet]$$

Conditions

N Gaussian random variables

- ① $X(t)$ has a finite constant mean \bar{X} for all t
- ② $X(t)$ is bounded $x(t) < \infty$ for all t and all $x(t)$
- ③ Bounded time average of $E[|X(t)|]$

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T E[|X(t)|] dt < \infty$$

- ④ $X(t)$ is a regular process

$$E[|X(t)|^2] = R_{XX}(t, t) < \infty$$

Regular process

N Gaussian random variables

$X(t)$ is a **regular process**

$$E \left[|X(t)|^2 \right] = R_{XX}(t, t) < \infty$$

for a real WSS process $X(t)$

$$E \left[|X(t)|^2 \right] = R_{XX}(0) < \infty$$

since \overline{X} is finite by assumption

$$C_{XX}(0) = R_{XX}(0) - \overline{X}^2 < \infty$$

Mean Ergodic

N Gaussian random variables

Definition

A wide sense stationary (WSS) process $X(t)$
 with a constant mean value \bar{X}

is called **mean-ergodic**

if the **time average** $\bar{x}_T = A_T[x(t)]$ converges to \bar{X} as $T \rightarrow \infty$

$$\lim_{T \rightarrow \infty} E[(\bar{x}_T - \bar{X})^2] = 0$$

$$\lim_{T \rightarrow \infty} \sigma_{\bar{x}_T}^2 = 0$$

Covariance Functions

N Gaussian random variables

Definition

$$\begin{aligned} C_{xx}(t, t + \tau) &= E[\{X(t) - m_X(t)\} \{X(t + \tau) - m_X(t + \tau)\}] \\ &= R_{xx}(t, t + \tau) - m_X(t)m_X(t + \tau) \end{aligned}$$

for a WSS process $X(t)$

$$\begin{aligned} C_{xx}(\tau) &= E[\{X(t) - \bar{X}\} \{X(t + \tau) - \bar{X}\}] \\ &= R_{xx}(\tau) - \bar{X}^2 \end{aligned}$$

Variance of \bar{X}_T (1)

N Gaussian random variables

$$\begin{aligned}\sigma_{\bar{X}_T}^2 &= E \left[\left\{ \frac{1}{2T} \int_{-T}^T (X(t) - \bar{X}) dt \right\}^2 \right] \\ &= E \left[\left(\frac{1}{2T} \right)^2 \left\{ \int_{-T}^T (X(t) - \bar{X}) dt \right\} \left\{ \int_{-T}^T (X(t_1) - \bar{X}) dt_1 \right\} \right] \\ &= E \left[\left(\frac{1}{2T} \right)^2 \int_{-T}^T (X(t) - \bar{X}) (X(t_1) - \bar{X}) dt dt_1 \right]\end{aligned}$$

Variance of \bar{X}_T (2)

N Gaussian random variables

$$\begin{aligned}\sigma_{\bar{X}_T}^2 &= E[(\bar{X}_T - \bar{X})^2] \\ &= \left(\frac{1}{2T}\right)^2 \int_{-T}^T \int_{-T}^T E[(X(t) - \bar{X})(X(t_1) - \bar{X})] dt dt_1 \\ &= \left(\frac{1}{2T}\right)^2 \int_{-T}^T \int_{-T}^T C_{XX}(t, t_1) dt dt_1\end{aligned}$$

for the WSS $X(t)$, let $C_{XX}(t, t_1) = C_{XX}(\tau)$, $\tau = t_1 - t$, and $d\tau = dt_1$

$$= \left(\frac{1}{2T}\right)^2 \int_{t=-T}^T \int_{\tau=-T-t}^{T-t} C_{XX}(\tau) d\tau dt$$

Variance of \bar{x}_T (3)

N Gaussian random variables

$$\sigma_{\bar{x}_T}^2 = \left(\frac{1}{2T}\right)^2 \int_{t=-T}^T \int_{\tau=-T-t}^{T-t} C_{XX}(\tau) d\tau dt$$

the Riemann strips in $\tau - t$ plane

- ① using horizontal Riemann strips
 - ② using vertical Riemann strips
- using the symmetry $C_{XX}(-\tau) = C_{XX}(\tau)$

$$\sigma_{\bar{x}_T}^2 = \frac{1}{2T} \int_{-2T}^{2T} \left(1 - \frac{|\tau|}{2T}\right) C_{XX}(\tau) d\tau$$

Variance of \bar{X}_T (4)

N Gaussian random variables

the necessary and sufficient condition
for a WSS process $X(t)$ to be mean ergodic

$$\lim_{T \rightarrow \infty} \left\{ \frac{1}{2T} \int_{-2T}^{2T} \left(1 - \frac{|\tau|}{2T} \right) C_{XX}(\tau) d\tau \right\} = 0$$

$$\frac{1}{2T} \int_{-2T}^{2T} \left(1 - \frac{|\tau|}{2T} \right) C_{XX}(\tau) d\tau < \frac{1}{2T} \int_{-2T}^{2T} |C_{XX}(\tau)| d\tau$$

- 1 $C_{XX}(0) < \infty$ and $C_{XX}(\tau) \rightarrow 0$ as $|\tau| \rightarrow \infty$
- 2 $\int_{-\infty}^{\infty} |C_{XX}(\tau)| d\tau < \infty$

Mean Ergodic Condition

N Gaussian random variables

Definition

a necessary and sufficient condition
for a WSS process $X(t)$ to be **mean ergodic**

$$\lim_{T \rightarrow \infty} \left\{ \frac{1}{2T} \int_{-2T}^{2T} \left(1 - \frac{|\tau|}{2T} \right) C_{XX}(\tau) d\tau \right\} = 0$$

Mean Ergodic Process - continuous time

N Gaussian random variables

Definition

$X(t)$ is a **mean ergodic** if

- 1 $C_{XX}(0) < \infty$ and $C_{XX}(\tau) \rightarrow 0$ as $|\tau| \rightarrow \infty$
- 2 $\int_{-\infty}^{\infty} |C_{XX}(\tau)| d\tau < \infty$

Mean Ergodic Process - discrete time

N Gaussian random variables

Definition

$X[n]$ is a mean ergodic if

$$\lim_{N \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{n=-N}^{+N} X[n] \right\} = \bar{X}$$

$$\lim_{T \rightarrow \infty} \left\{ \frac{1}{2N+1} \sum_{n=-2N}^{+2N} \left(1 - \frac{|n|}{2N+1} \right) C_{XX}[n] \right\} = 0$$

Auto-correlation Ergodic Process - Continuous Time

N Gaussian random variables

Definition

A stationary continuous process $X(t)$ with autocorrelation function $R_{XX}(\tau)$ is called **autocorrelation ergodic** if for all τ , $R_T(\tau) = A_T[x(t)x(t+\tau)]$ converges to $R_{XX}(\tau)$ as $T \rightarrow \infty$

Auto-correlation Ergodic Process - Discrete Time

N Gaussian random variables

Definition

A stationary sequence $X[n]$
with autocorrelation function $R_N[k]$
is called **autocorrelation ergodic**
if for all k , $R_N[k] = \frac{1}{2N+1} \sum_{n=-N}^{+N} x[n]x[n+k]$
converges to $R_{XX}[k]$ as $N \rightarrow \infty$

A necessary and sufficient condition

N Gaussian random variables

Definition

$$W(t) = X(t)X(t + \tau)$$
$$E[W(t)] = E[X(t)X(t + \tau)] = R_{XX}(\tau)$$

$$R_{WW}(\lambda) = E[W(t)W(t + \lambda)]$$
$$= E[X(t)X(t + \tau)X(t + \lambda)X(t + \tau + \lambda)]$$

$$C_{WW}(\lambda) = R_{WW}(\lambda) - \{E[W(t)]\}^2$$
$$= R_{WW}(\lambda) - R_{XX}^2(\tau)$$

Auto-correlation Ergodic Condition

N Gaussian random variables

Definition

a necessary and sufficient condition
for a WSS process $X(t)$ to be **auto-correlation ergodic**

$$\lim_{T \rightarrow \infty} \left\{ \frac{1}{2T} \int_{-2T}^{2T} \left(1 - \frac{|\tau|}{2T} \right) C_{WW}(\tau) d\tau \right\} = 0$$

Auto-correlation Ergodic

N Gaussian random variables

- auto-correlation ergodicity requires that the 4-th order moments of $X(t)$

$$R_{WW}(\lambda) = E[X(t)X(t+\tau)X(t+\lambda)X(t+\tau+\lambda)]$$

- for Gaussian processes, 4-th order moments are known via 2nd and 1st order moments

